

Homework 20 MATH 304 Section 3

Assigned: Friday, November 14.
 Potentially Collected: Friday, November 21.

- Let V be the vector space with basis $S = (1, t, e^t, te^t)$ and note that V is a subspace of the vector space of differentiable real functions. Let $L : V \rightarrow V$ be the linear transformation where $L(f(t)) = f'(t)$ for any differentiable function f . Find ${}_S L_S$.
- Let $F : \mathbb{P}_1 \rightarrow \mathbb{P}_2$ be the linear transformation where $F(p(x)) = xp(x) + p(0)$ for any degree one polynomial p . Consider the bases $S = (x, 1)$ and $R = (x+1, x-1)$ for \mathbb{P}_2 and $A = (x^2, 1, x)$ and $B = (x^2+1, x-1, x+1)$ for \mathbb{P}_3 . $E_1 = (1, x)$ $E_2 = (1, x, x^2)$
 - Find the standard matrix for F and then calculate ${}_{A S} F$ and ${}_{B R} F$ using change of basis matrices.
 - Calculate $F(-3x-3)$ for each of the three matrices of (a).
- Let $L : M_{22} \rightarrow M_{22}$ be the linear transformation between the vector space of 2×2 real matrices where $L(A) = \left(\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} A \right)$ for any 2×2 real matrix A . Let

$$S = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

$$T = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\}$$

- Show that S and T are bases for M_{22} .
- Find ${}_S L_S$, ${}_T L_T$, ${}_S L_T$, and ${}_T L_S$.

① ${}_S L_S = \begin{bmatrix} K_S L(1) & K_S L(t) & K_S L(e^t) & K_S L(te^t) \end{bmatrix}$
 $= \begin{bmatrix} K_S(0) & K_S(1) & K_S(e^t) & K_S(te^t + e^t) \end{bmatrix}$
 $= \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ ← let $f(t) = 1 + t + e^t + te^t$
 $L(f(t)) = 0 + 1 + e^t + te^t + e^t$

② ${}_{E_2} F_{E_1} = \begin{bmatrix} K_{E_2} F(1) & K_{E_2} F(x) \end{bmatrix}$
 $= \begin{bmatrix} K_{E_2}(x+1) & K_{E_2}(x^2) \end{bmatrix}$
 $= \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

by derivatives.
 $L(f(t)) = K_S^{-1} ({}_S L_S) K_S (f(t))$
 $= K_S^{-1} \left(\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right)$
 $= K_S^{-1} \left(\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right) = 1 + 2e^t + te^t$

$$A I_{E_2} = [K_A(1) \quad K_A(x) \quad K_A(x^2)]$$

Solve $\vec{w} = a_1(x^2) + a_2(1) + a_3(x) = a_2 + a_3x + a_1x^2$

to find $K_A(\vec{w}) = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$. Solve $\begin{bmatrix} 0 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & 0 & 1 & 0 \\ 1 & 0 & 0 & | & 0 & 0 & 1 \end{bmatrix}$

$$A I_{E_2} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\hookrightarrow \begin{bmatrix} 1 & 0 & 0 & | & 0 & 0 & 1 \\ 0 & 1 & 0 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & 0 & 1 & 0 \end{bmatrix}$$

$$B I_{E_2} = [K_B(1) \quad K_B(x) \quad K_B(x^2)]$$

Solve $\vec{w} = a_1(x^2+1) + a_2(x-1) + a_3(x+1) = (a_1 - a_2 + a_3)$

$+ (a_2 + a_3)x + (a_1)x^2$

Solve $\begin{bmatrix} 1 & -1 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & 1 & | & 0 & 1 & 0 \\ 1 & 0 & 0 & | & 0 & 0 & 1 \end{bmatrix}$ to obtain $B I_{E_2} = \begin{bmatrix} 0 & 0 & 1 \\ .5 & .5 & .5 \\ .5 & .5 & -.5 \end{bmatrix}$

$$E_1 I_S = [K_{E_1}(x) \quad K_{E_1}(1)] = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$E_1 I_R = [K_{E_1}(x+1) \quad K_{E_1}(x-1)] = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$A F_S = (A I_{E_2})(E_2 F_{E_1})(E_1 I_S) = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$B F_R = (B I_{E_2})(E_2 F_{E_1})(E_1 I_R) = \begin{bmatrix} 0 & 0 & 1 \\ .5 & .5 & .5 \\ .5 & .5 & -.5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 1 \\ .5 & .5 & .5 \\ .5 & .5 & -.5 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ .5 & .5 \\ .5 & -1.5 \end{bmatrix}$$

$$\textcircled{b} \quad {}_A F_S = K_A F K_S^{-1} \Rightarrow F = K_A^{-1} ({}_A F_S) K_S$$

$$\begin{aligned} \text{so } F(-3x-3) &= K_A^{-1} ({}_S F_A) K_S (-3x-3) \\ &= K_A^{-1} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -3 \\ -3 \end{bmatrix} \right) = K_A^{-1} \left(\begin{bmatrix} -3 \\ -3 \end{bmatrix} \right) \\ &= -3(x^2) - 3(1) - 3(x) = -3 - 3x - 3x^2 \end{aligned}$$

$${}_B F_R = K_B F K_R^{-1} \Rightarrow F = K_B^{-1} ({}_B F_R) K_R$$

$$\begin{aligned} \text{so } F(-3x-3) &= K_B^{-1} ({}_B F_R) K_R (-3x-3) \\ &= K_B^{-1} ({}_B F_R) \begin{bmatrix} -3 \\ 0 \end{bmatrix} \\ &= K_B^{-1} \left(\begin{bmatrix} -3 \\ -1.5 \\ -1.5 \end{bmatrix} \right) = -3 - 3x - 3x^2 \end{aligned}$$

$\left\{ \begin{array}{l} -3x-3 = a(x+1) + b(x-1) \\ \quad \quad \quad = (a+b)x + (a-b) \\ \text{solve } \begin{bmatrix} 1 & 1 & -3 \\ 1 & -1 & -3 \end{bmatrix} \end{array} \right.$

$${}_{E_2} F_{E_1} = K_{E_2} F K_{E_1}^{-1} \Rightarrow F = K_{E_2}^{-1} ({}_{E_2} F_{E_1}) K_{E_1}$$

$$\begin{aligned} \text{so } F(-3x-3) &= K_{E_2}^{-1} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} K_{E_1} (-3x-3) \\ &= K_{E_2}^{-1} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -3 \\ -3 \end{bmatrix} = K_{E_2}^{-1} \left(\begin{bmatrix} -3 \\ -3 \end{bmatrix} \right) \\ &= -3 - 3x - 3x^2 \end{aligned}$$

③ Is $S \perp I$? solve $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

only trivial solution

$$\text{Span}(S) = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mid a, b, c, d \in \mathbb{R} \right\} = M_{22}$$

Therefore, S is a basis for M_{22} .

Is $T \perp I$? solve $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} a+b+c & b+d \\ c & a \end{bmatrix}$$

$$\begin{aligned} \hookrightarrow & \Rightarrow c=0 \\ & a=0 \\ & b=0 \\ & d=0 \end{aligned} \quad \text{only trivial solution}$$

As $\dim(\text{span}(T)) = 4 = \dim(M_{22})$

we have that T is a basis for M_{22} .

$$\begin{aligned} SL_S &= [K_S L(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}) \quad K_S L(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}) \quad K_S L(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}) \quad K_S L(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix})] \\ &= [K_S(\begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix}) \quad K_S(\begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix}) \quad K_S(\begin{bmatrix} 2 & 0 \\ 4 & 0 \end{bmatrix}) \quad K_S(\begin{bmatrix} 0 & 2 \\ 0 & 4 \end{bmatrix})] \\ &= \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 2 \\ 0 & 3 & 4 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}
 T L_T &= [K_T L \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right)] \\
 &= [K_T \left(\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 1 & 1 \\ 3 & 3 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 3 & 0 \\ 7 & 0 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} \right)] \\
 &= \begin{bmatrix} 4 & 3 & 0 & 3 \\ -6 & -5 & -4 & -3 \\ 3 & 3 & 7 & 0 \\ 8 & 6 & 4 & 4 \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 S L_T &= [K_S L \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) K_S L \left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \right) K_S L \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) K_S L \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right)] \\
 &= [K_S \left(\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \right) K_S \left(\begin{bmatrix} 1 & 1 \\ 3 & 3 \end{bmatrix} \right) K_S \left(\begin{bmatrix} 3 & 0 \\ 7 & 0 \end{bmatrix} \right) K_S \left(\begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} \right)] \\
 &= \begin{bmatrix} 1 & 1 & 3 & 0 \\ 2 & 1 & 0 & 1 \\ 3 & 3 & 7 & 0 \\ 4 & 3 & 0 & 3 \end{bmatrix}
 \end{aligned}$$

$$\begin{aligned}
 T L_S &= [K_T L \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right) K_T L \left(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right)] \\
 &= [K_T \left(\begin{bmatrix} 1 & 0 \\ 3 & 0 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 0 & 1 \\ 0 & 3 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 2 & 0 \\ 4 & 0 \end{bmatrix} \right) K_T \left(\begin{bmatrix} 0 & 2 \\ 0 & 4 \end{bmatrix} \right)] \\
 &= \begin{bmatrix} 0 & 3 & 0 & 4 \\ -2 & -3 & -2 & -4 \\ 3 & 0 & 4 & 0 \\ 2 & 4 & 2 & 6 \end{bmatrix}
 \end{aligned}$$